Mars Exploration Rover Mission



Spirit and Opportunity celebrated 500 sols on Mars!



Spirit navigation camera, June 3, 2005 (sol 503). NASA/JPL



Opportunity navigation camera, June 22, 2005 (sol 501). NASA/JPL

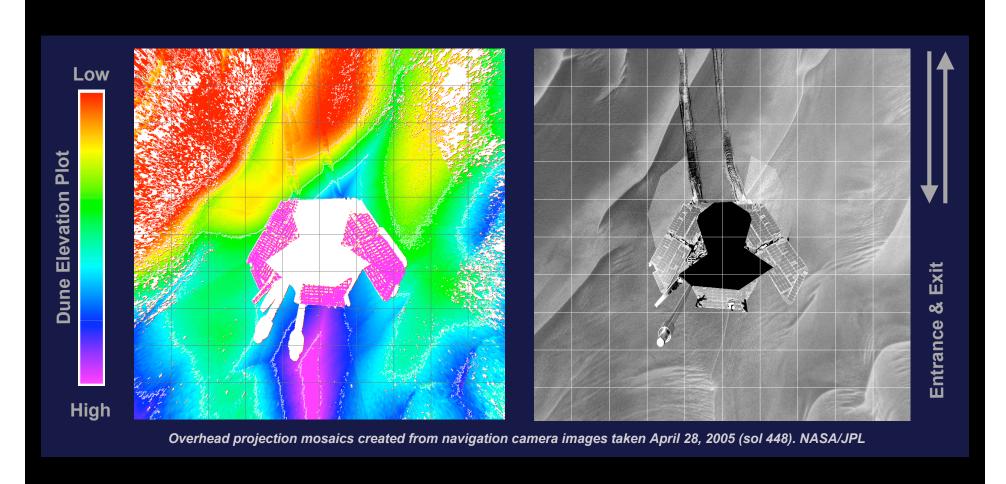
The rovers have survived over four times their life-expectancy goals on Mars.

Opportunity survived the trap of "Purgatory Dune," inching free of its 5-week hold in wheel-sinking sand!



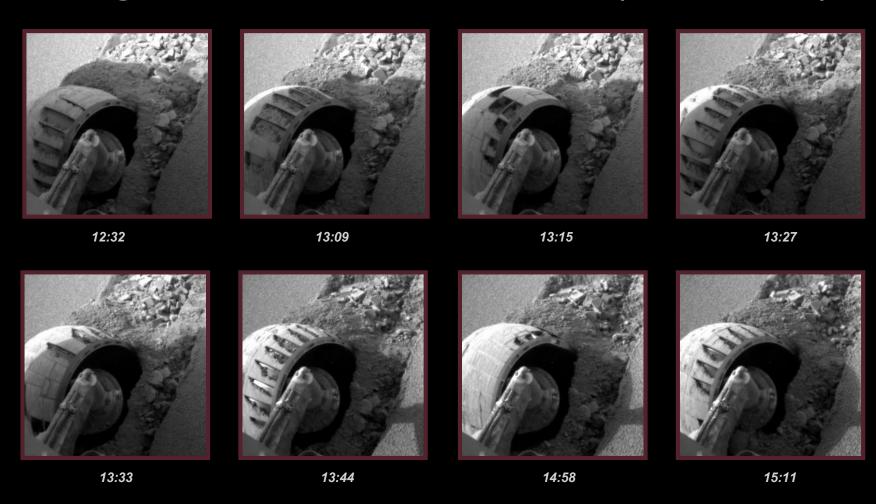
Navigation camera, June 11, 2005 (sol 491). NASA/JPL

Mobility engineers decided the safest route to exit Purgatory was to go back the way they came.



Opportunity had been driving backwards when it entered the dune, and then drove out moving forward.

As Opportunity churned the first three feet out of the slippery dune, the wheels spun enough times to have moved 581 feet (177.2 meters).



Once Opportunity was safe on higher ground, the team sent the rover BACK to Purgatory Dune!



Mobility engineer Mark Maimone next to the test rover in the "Mars Sandbox" at JPL.

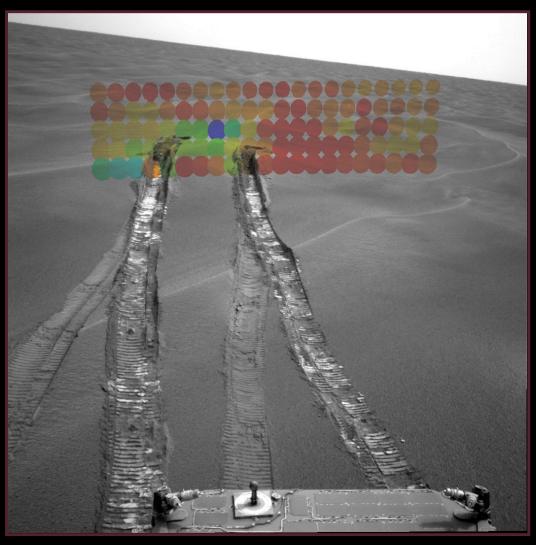
Rover drivers wanted to figure out how to steer clear of another dune ambush.

Science team members also wanted to characterize Purgatory Dune to understand why this ripple stopped the rover when others had not.



False-color panoramic camera image, June 16 (sol 496). NASA/JPL/Cornell

One theory from the Mini-TES team is that temperature can give clues to potential "stuck spots."



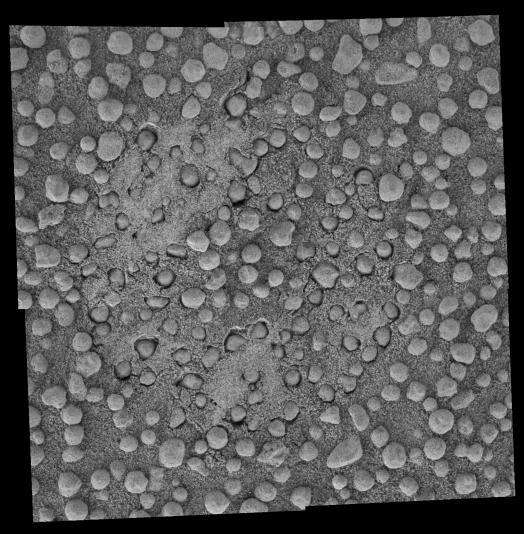
Looking back, the rover got stuck in a spot that was cooler than elsewhere.

That might indicate that a surface crust covered finer grained sand beneath that the rover couldn't at first escape.

Cool



Team members are still analyzing the science data from Purgatory Dune.



Microscopic Imager mosaic of "Troughplain," June 26, 2005 (sol 505). NASA/JPL/Cornell

While Opportunity's view of the sand caused a bit of stress, the rover's view of the sky was awe-inspiring.



Panoramic camera, April 29, 2005 (sol 449).

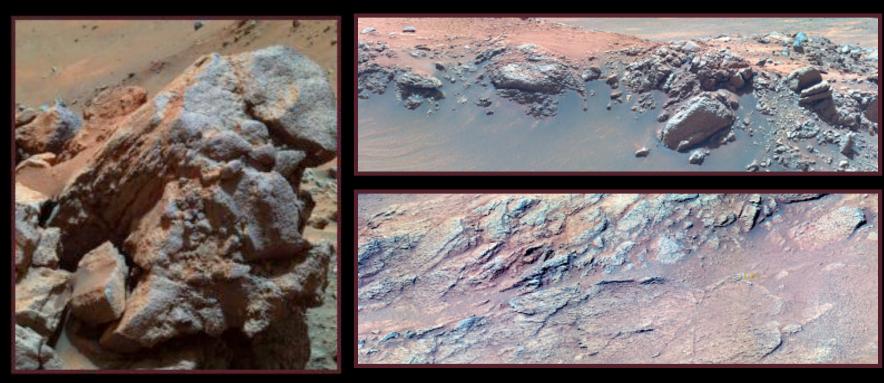
> **Opportunity viewed Earth at twilight.** Earth appears elongated because it moved slightly during the 15-second camera exposures.

On the opposite side of Mars, Spirit captured the Sun setting against the rim of Gusev Crater!



Panoramic camera, May 19, 2005 (sol 489). NASA/JPL/Cornell/Texas A&M

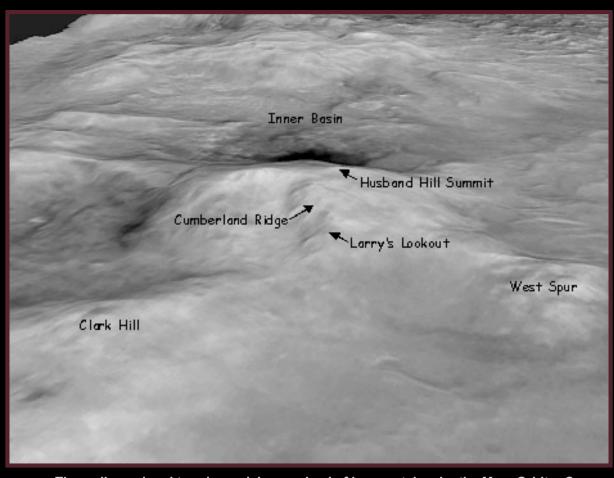
Spirit also investigated more rocks at Larry's Outcrop, Jibsheet, and Methuselah.



False-color panoramic camera, May 2005. Larry's Outcrop (left), Jibsheet (top right), Methuselah (bottom right). NASA/JPL/Cornell

The rocks basically have the same chemical composition, but show huge diversity in texture, probably because they were altered by the martian environment in different ways.

Spirit is striking out toward new territory, and the team is now faced with the decision whether or not to attempt to reach the summit of Husband Hill.



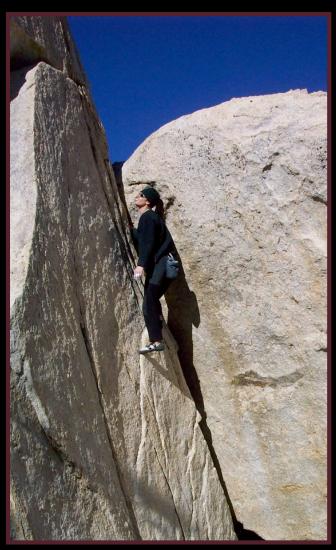
Three-dimensional terrain model comprised of images taken by the Mars Orbiter Camera on Mars Global Surveyor, processed by the U.S. Geological Survey.

NASA/JPL/MSSS/USGS/NMMNH

Many rover team members are fans of mountaineering on both Earth and Mars, but are cautious about making the best science decisions for Spirit.



Principal Investigator, Steve Squyres, ice climbing near Ithaca, New York.



Rover driver, Chris Leger, bouldering at Horse Flats near Pasadena, California.

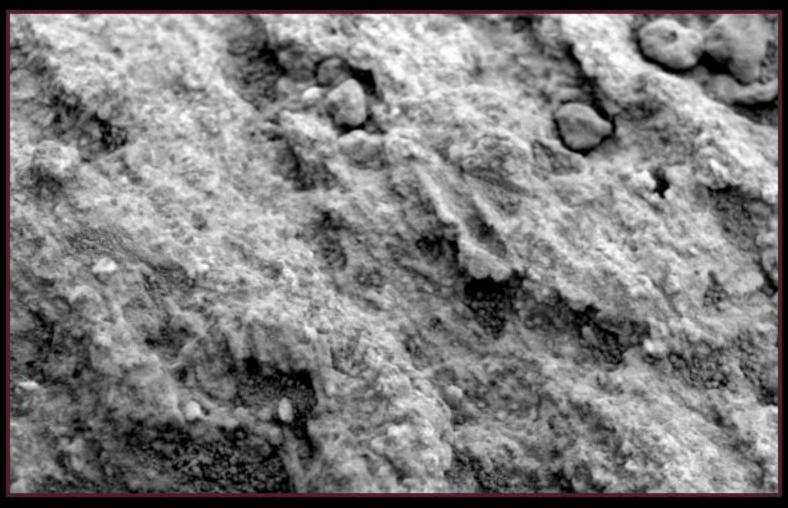
Spirit is currently cruising on firm ground at Gusev, which makes for great traction and great climbing.



But, it looks like the terrain will transition to softer ground near the summit of Husband Hill.

Navigation camera, June 28, 2005 (sol 528). NASA/JPL

While the team weighs the value versus the risk of going to the top of Husband Hill, Spirit will spend the 4th of July weekend studying a layered rock named "Independence."

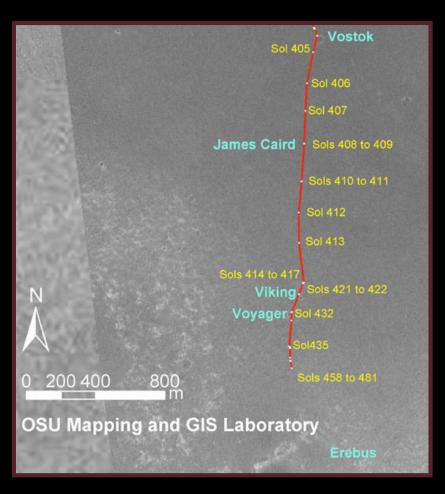


Microscopic Imager, June 29, 2005 (sol 529). NASA/JPL/Cornell



After the holiday weekend, Spirit's team will decide whether to aim for the summit.

Opportunity will travel north for safety, then head south toward the etched terrain of Erebus.



Opportunity orbital traverse map. NASA/JPL/MSSS